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RESEARCH OF VOLTAGE DEVIATION IN RURAL ELECTRICAL GRID WITH DISTRIBUTED GENERATION

Abstract. In accordance with the strategy for the development of energy in Kazakhstan in agriculture, it is necessary to solve the important problem of reducing the energy intensity of agricultural production [1, 2]. The key difficulties in integrating high-capacity generation of renewable energy sources (RES) into the grid are the planning and management of the system. Scenarios for studying the impact on the system depend on high or low load, high proportion or absence of wind/solar energy. For each case, the bus voltage is calculated and checked for compliance with permissible limits, the calculation of the flow distribution of active and reactive power, as well as losses in the transformer, on power lines, generators and other components. Most wind and solar power plants do not provide inertial response or control of statism [3]. A number of difficulties arise related to the stability of the voltage in transient modes. In this regard, the actual issue is the introduction of adaptive controllers for controlling inverters, depending on the change in the mode parameters [4, 5]. In this paper, we present the results of studies on the modeling of transient regimes using the example of the SPP with an installed capacity of 2 MW describes the possibility of changing the principles of system management, which is the most economical solution to the problems of integrating wind and photovoltaic solar energy into a network. The virtual model of the PSCad analyzed the stability of the voltage in the event of a short circuit on the 10 kV bus, algorithms and mechanisms for using the intelligent controller for controlling the photovoltaic system were developed.

Keywords: distributed generation, integration of solar power plants, voltage deviation, transient modes, short-circuit current.

Introduction. The current state policy on the introduction of green and clean technologies encourages the construction of renewable energy sources, such as wind farms, solar power plants (SPP) and small hydropower plants. According to the data presented in [6, 7], by the end of 2025, it is expected to connect more than 3,000 MW of RES or 15% of the total installed capacity of the generating stations of the Republic. Including, the share of SPP will be 650 MW. With the increase in the share of RES in the total balance of capacity, electromagnetic processes in systems with power converters have a significant effect on voltage stabilization. It is known that the occurrence of a short circuit (SC) due to an unstable damage inevitably leads to a voltage drop in one or several phases (possibly also to a voltage jump in undamaged phases), depending on the type and location of the fault. For this reason, the grid rules of countries with developed renewable energy require that the connection of a high-power RES-power system keep the voltage drop in the network to a certain level (usually in percentage of the nominal voltage) without switching off.

Since 2015, the system operator of KEGOC JSC for the reconciliation of the scheme for issuing the power of renewable energy has introduced "System operator requirements for ensuring integration of RES with the energy system" [8, 9], where one of the main requirements is to ensure the stability of RES voltage in transient modes. The document contains the conditions for RES operation when the linear (phase-to-phase) voltage falls at the point of connection to the network caused by the asynchronous mode in the adjacent network or by close short circuits (symmetrical or asymmetric) [9]. The required voltage value is provided by generating a controlled volume of reactive power. Figure 1 shows the "voltage-time" characteristic at the time of the accident.

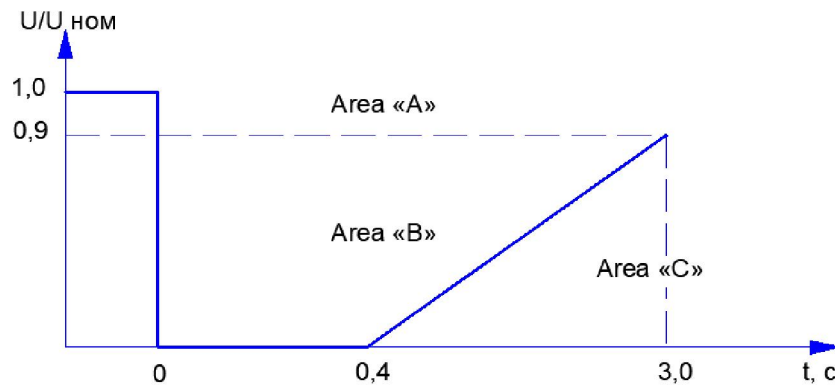


Figure 1 – Diagram of restrictions of switching off generating plants from the common network in the parameters of level-duration of voltage drop

Area "A" - RES must remain connected to the network and function steadily;

Area "B" - RES must remain connected to the network and provide maximum voltage support by generating a controlled volume of reactive power;

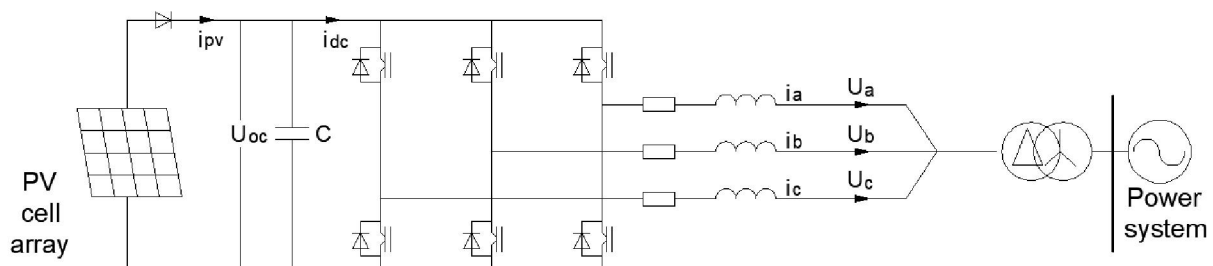
Area "C" - it is allowed to disconnect RES from the network.

Thus, it is required that the RES object in case of voltage drop to 0 in the time interval between 0.4s and 3s remains connected to the power system (zone B) or be disconnected (zone C) from the external network as the voltage deviation U/U_{nom} changes curve on figure 1.

For solar power plants, provision of permissible voltage is possible due to adaptive regulation of the inverter's operation, the task of which is to receive the reactive component from the network to stabilize the voltage when increasing and to generate reactive power with an unacceptable voltage drop. The change in the value of $\cos(\varphi)$ should be within 0.85 ind and 0.85 cap [10]. The results of the studies presented in [3-5, 10, 11] show that providing a voltage within a given range is one of the most difficult tasks, the solution of which depends on changing climatic conditions (humidity, wind, solar radiation, etc.) temperature heating of cells, as well as the number of solar panels at the station, affecting the fluctuations in output power. For SES connected to an external electrical network (on-line), the provision of permissible voltage levels in normal and post-emergency modes is possible at the expense of power storage devices, but the cost of such installations is not yet sufficiently acceptable for companies [10].

In this regard, an effective means of voltage regulation is the use of an intelligent regulator for controlling the photovoltaic power supply system [4]. However, the use of this approach requires the development of adaptive algorithms that will in real time regulate the conversion of active and reactive current in inverters depending on the voltage level on the bus bars of the connected external network.

In this article, studies have been conducted to maintain the voltage inverters of the 2-MW SPP like as in Kapshagai city in the south of Kazakhstan in the event of a short-circuit occurring in the PSCADTM software package. PSCAD is a high-speed, accurate to 0.001s. and a simple tool for modeling the operation of power systems and power electronic converters in their design, analysis, optimization and verification. and also proposed algorithms and mechanisms for ensuring stable operation of the power system in transient regimes.



This SPP is connected to an external 10 kV network via a 0.4/10 kV step-up transformer. The voltage variation in the transient regimes was estimated under the conditions of the occurrence of a 3-phase short circuit (short circuit) on the 10 kV busbars of a 1-second transformer substation. Modeling is performed in the PScad TM software package. The PScad program with the EMTDC TM transient simulation module provides a wide range of tools and a large component library for detailed analysis of the operation of power equipment. The result of the system simulation are graphs of the transients of currents and voltages at the input and output of the system for both ac networks and for the DC transmission system. The line parameters are given in the form of lumped inductances, capacitance and resistances, equivalent to the physical parameters of the line.

Results and discussion. To model the SPP, the structural diagram of which is shown in figure 2, we write the output voltage at the solar power plant in a matrix form for 3 phases (2):

$$\begin{bmatrix} U_{sa} \\ U_{sb} \\ U_{sc} \end{bmatrix} = (R + L \frac{d}{dt}) \begin{bmatrix} i_a \\ i_b \\ i_c \end{bmatrix} + \begin{bmatrix} u_a \\ u_b \\ u_c \end{bmatrix} \quad (1)$$

where U_{sa} , U_{sb} , U_{sc} is the voltage of the inverter, i_a , i_b , i_c is the inverter current, u_a , u_b , u_c is the voltage of the external electrical network.

In accordance with the requirements of transmitting electrical networks [9], it is necessary that at the time of transient regimes the accident does not spread to distribution networks and does not provoke its cascade development.

Voltage stability in PV systems is determined by the operation of inverters, which must regulate the generation of active and reactive power during short-circuit or other transient processes [11]. The mathematical model of the inverter operation is described by the following equations (3, 4) in the simplified coordinate system d , q :

$$u_{sd} = Ri_d + L \frac{di_d(t)}{dt} - \omega Li_q + u_d \quad (2)$$

$$u_{sq} = Ri_q + L \frac{di_q(t)}{dt} + \omega Li_d - u_q$$

$$\begin{aligned} P &= u_d i_d + u_q i_q \\ Q &= u_q i_q - u_d i_d \end{aligned} \quad (3)$$

From figure 3A, we can observe that after a 3-phase short circuit on a 10kV bus, the inverter goes into protection mode and automatically removes the voltage at the output, the instantaneous and active voltage on the 10kV buses is reduced to 0 and restored only after the short circuit is completed. There is a decrease in the generated currents, and accordingly the active and reactive power from the SPP. For 1 second SPP does not contribute to the external power supply voltage. When the external voltage drops to a critical level, the SPP automatics takes it to isolated work in order to ensure the stable operation of the integrated electric network.

Analysis of simulation of transient modes shows that as a result of the absence of a reverse electro-mechanical connection of the power system from the SES, intelligent regulators must be used to control the output voltage, which will adaptively control the generation of active and reactive power when the external parameters of the electrical network change. Figure 4 shows the block diagram of Iq operation of the regulator for operation in the SPP system when connected to an external electrical network.

Models of automatic systems based on semiconductor converters with pulse-width modulation belong to the class of systems of the following type [8]:

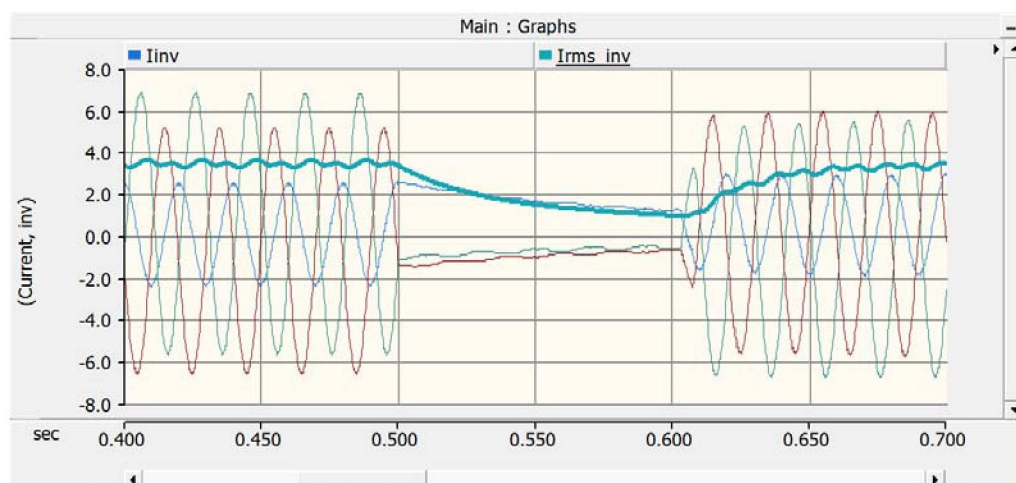
$$\frac{dX}{dt} = G(A, \bar{X}, t), \quad (4)$$

where X is a vector of phase variables; G is a periodic vector function; A is the matrix of the parameters of the system.

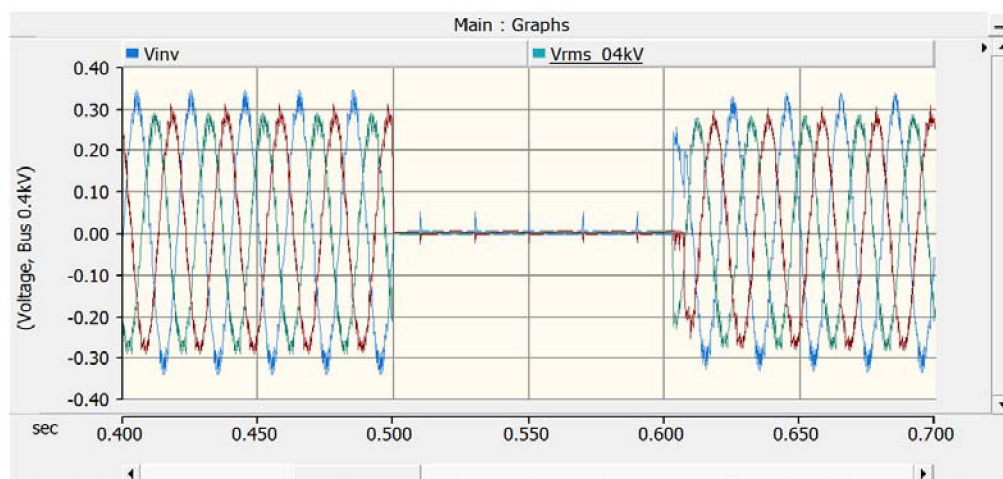
The solution of the system (1) has the form:

$$\bar{X}(t) = \bar{X}(t + T).$$

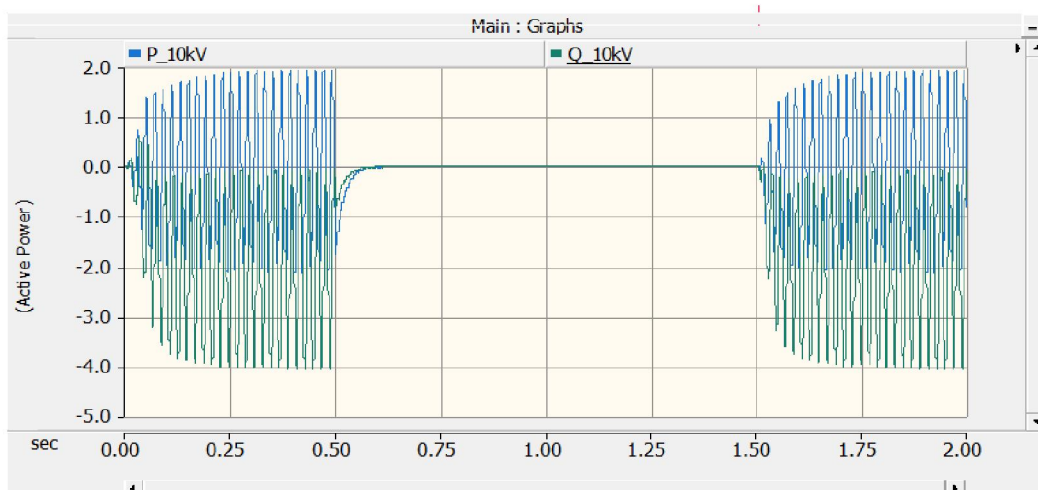
The converter replacement circuit is described by a system of nonlinear differential equations



A



B



C

Figure 3 – Oscillograms of transient processes with a 3-phase short-circuit fault with a duration of 1 sec on buses substation 10 kV with a connected SPP. A – instantaneous and effective values of currents B – instantaneous and effective values of voltages, C – active values of active and reactive power

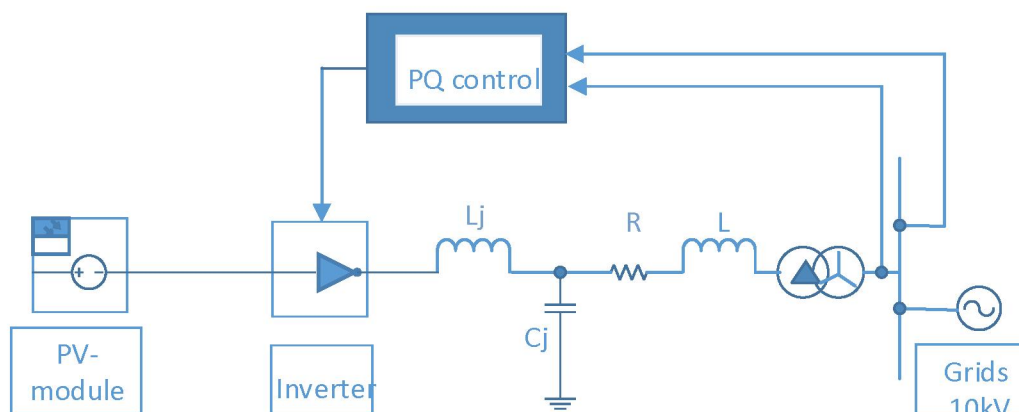


Figure 4 – Block diagram of the Iq controller operation in the SPP system when connected to an external network

$$\begin{cases} L \frac{di_L}{dt} = -R \cdot i_L - K_{FD}(\xi(t)) \cdot u_C + E; \\ C \frac{du_C}{dt} = i_L \cdot K_{FD}(\xi(t)) - \frac{u_C}{R_H}, \end{cases} \quad (5)$$

where i_L is the current in the inductance; u_C - voltage on the filter capacity; $\xi(t)$ - a function that describes the commutation of a diode.

In the matrix form, system (4) is written as

$$\frac{d\bar{X}}{dt} = A(K_F(\xi(t))) \cdot \bar{X} + \bar{B}(i_L).$$

The principle of the Iq regulator operation is to control the external voltage of the network and to regulate the operation of the inverter by generating active and reactive transients in the event of a fault (5).

$$u_{a,b,c} = U_{sa,sb,sc} - (Ri_d + L \frac{di_d}{dt}) \quad (6)$$

The operation of the inverter for regulating the generation of active and reactive power will be performed in accordance with the model in the coordinates dq from the change in the phase of the external current ωLi_q , $-\omega Li_d$ (6).

$$\begin{aligned} u_d &= U_{sd} - \left(Ri_d(t) + L \frac{di_d(t)}{dt} \right) + \omega Li_q(t) \\ u_q &= U_{sq} - \left(Ri_q(t) + L \frac{di_q(t)}{dt} \right) - \omega Li_d(t) \end{aligned} \quad (7)$$

The purpose of voltage regulation at the connection point is to provide the required voltage in accordance with the graph shown in Fig. 1. To do this, Iq controller is used, which determines the current value on the inverter i_m using the system of equations 6.

To determine the currents $X(i_d, i_q)$, we use the solution of linear equations in the form:

$$\bar{X}(t) = \bar{Y} \cdot A^{-1}, \quad (8)$$

where \bar{Y} – is the vector of voltage drops in the network between the points of connection of the SPP to the system in the coordinates d, q; \bar{X} – current vector in the coordinates d, q; A – matrix parameters (step-up transformer, cable, etc.) between the point U_{out} and the point of connection of SPP to the system buses.

$$\begin{cases} Y_d \geq (U_{sd} - U_d) / U_{sdndu}; \\ Y_q = (U_{sq} - U_q) / U_{sqndu}. \end{cases} \quad (9)$$

The solution of system (8) has the form:

$$\bar{X}(t) = \bar{X}(t + T), \quad (10)$$

where $Y_s = \sqrt{Y_d^2 + Y_q^2}$, determined by the shutdown conditions:

$$\begin{cases} Y_s \geq Y_{snom} \text{ where } t \equiv (t_0; t_\infty); \\ Y_s = 0 \text{ where } t < 0.4s; \\ Y_s = Y_0 + k \cdot t, \text{ where } k = tg(\Delta U / t). \end{cases} \quad (11)$$

As a result of the developed adaptive algorithm, the necessary level of output voltage of the PV system will be provided in the Iq regulator functioning in order to stabilize the transients of the external power system.

Conclusion. In this paper, some possibilities of distributed generation to regulate voltage and control reactive power were shown, but still many questions require investigation. One of them is economic efficiency, because such an approach increases losses in distribution grid. With significant integration of SES and the absence of a reverse electromechanical connection with the power system, it is necessary to use the development of a voltage regulator at SPP based on the parameters of the external network mode, based on adaptive algorithms for controlling the operation of inverters. The voltage regulator on SPP is implemented in the form of Iq controller, which affects the current of the inverter i_m . An algorithm for determining the required current value is proposed using the equation of the current dependence on the voltage drop between the U_{out} point and the SPP connection point to the system buses. In addition, different combinations of control for large and small-scale PV plants are possible to consider as well as an implementation of central control for all renewables in the distributed grid. This direction will be also investigated in the nearest future.

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МВТ ҚУАТТЫЛЫҚТАҒЫ КҮНЭЛЕКТРСТАНЦИЯСЫН ИНТЕГРАЛДАУ КЕЗІНДЕГІ ТАРАТУШЫ ЖЕЛІЛЕРДЕГІ КЕРНЕУ ТҰРАҚТЫЛЫҒЫНЫҢ ЗЕРТТЕУІ

Аннотация. Қазақстанда жаңартылатын энергия көздерін енгізуді ынталандыру бойынша бірқатар шаралар қабылданды, олардың біреуі күнэнергиясы болып табылады [1, 2]. Көптеген жел және күнэлектр-станциялары (КЭС) инерциалды жауап беруді немесе статистиканы бақылауды қамтамасыз етпейді. Қайта кернеу кернеуінің инверторы сыртқы электрмен жабдықтау жүйесінің кернеуімен кері байланыс жоқ. СЭС-нің электрэнергиясын өндіруі, әдетте, тек күн радиациясының функциясы болып табылады және желі жұмысының параметрлеріне байланысты емес [3]. Осыған байланысты, инверторларды басқаруға бейімделген контроллерлерді режимнің параметрлерін өзгертуге байланысты [4, 5] енгізу мәселесі өзекті болып табылады. Жаңартылатын энергия көздерін жоғары қуаттылықты торға интеграциялаудың негізгі қиындықтары жүйені жоспарлау және басқару болып табылады. Жүйеге әсерді зерттеу үшін сценарийлер жоғары немесе төмен жүктемеден, жоғары пропорциядан немесе жел/күн энергиясының жоқтығына байланысты. Әрбір жағдайда шиналардың кернеуі рұқсат етілген лимиттерге, белсенді және реактивті қуатты нағынын бөлу, сондай-ақ трансформатордағы, электржелілерінде, генераторлардағы және басқада құрамдас бөліктеріндегі шығындардың есептелуі үшін есептеледі және тексеріледі. Осы мақалада белгіленген қуаты 2 МВт болатын Қапшағай күнэлектрстанциясының мысалында өтпелі режимдерді модельдеу бойынша зерттеулер нәтижелерін ұсынамыз. PSCad виртуалды компьютерлік модельде 10 кВ-тық шиналарда қысқа тұйықталу жағдайында кернеу тұрақтылығыталданды, фотоэлектрлік жүйені басқару үшін интеллектуалды контроллерді қолдану үшін алгоритмдермен механизмдер әзірленді.

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ИССЛЕДОВАНИЕ СТАБИЛЬНОСТИ НАПРЯЖЕНИЯ В РАСПРЕДЕЛИТЕЛЬНЫХ СЕТЯХ ПРИ ИНТЕГРАЦИИ СОЛНЕЧНОЙ ЭЛЕКТРОСТАНЦИИ МОЩНОСТЬЮ 2 МВт

Аннотация. В Казахстане предпринят ряд мер по стимулированию ввода возобновляемых источников энергии (ВИЭ), одним из которых является солнечная энергетика [1, 2]. Большинство ветровых и солнечных электростанций (СЭС) не обеспечивают инерционный отклик или контроль статизма. Преобразовательные инверторы напряжения не имеют обратной связи с напряжением системы внешнего электроснабжения. Генерация мощности СЭС, как правило, является только функцией солнечного излучения и не зависит от режимных параметров сети [3]. В связи с этим, актуальным является вопрос внедрения адаптивных контроллеров по управлению инверторами в зависимости от изменения параметров режима [4, 5]. Ключевыми трудностями при интеграции больших мощностей генерации ВИЭ в энергосистему являются планирование и управление системой. Сценарии для изучения воздействия на систему зависят от высокой или низкой нагрузки, высокой доли или отсутствия ветряной /солнечной энергии. Для каждого случая рассчитывается напряжение на шине и проверяется на соответствие допустимым пределам, проводится расчет потоков распределения активной и реактивной мощности, а также потерь в трансформаторе, на ЛЭП, генераторах и других компонентах. В настоящей работе приведены результаты исследований по моделированию переходных режимов на примере Капшагайской солнечной станции (СЭС) установленной мощностью 2 МВт. В виртуальной модели ПК PSCad проанализирована стабильность напряжения при возникновении короткого замыкания на шинах 10 кВ, разработаны алгоритмы и механизмы по использованию интеллектуального регулятора для управления фотовольтаической системой.

Ключевые слова: распределенная генерация, стабильность напряжения, интеграция СЭС, переходные процессы, ток короткого замыкания.

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